

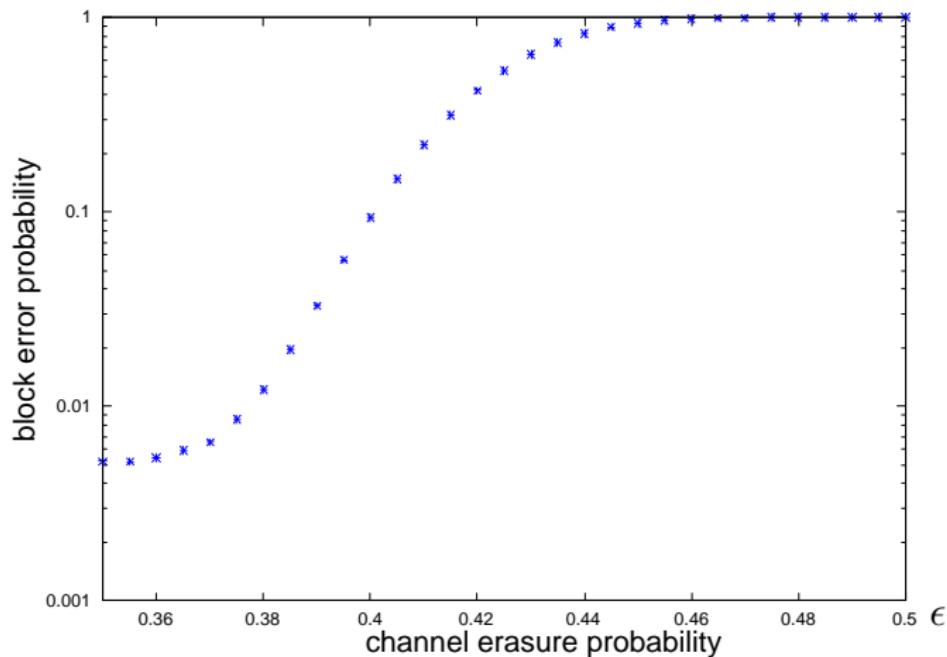
Analytical Solution of Covariance Evolution for Regular LDPC Codes

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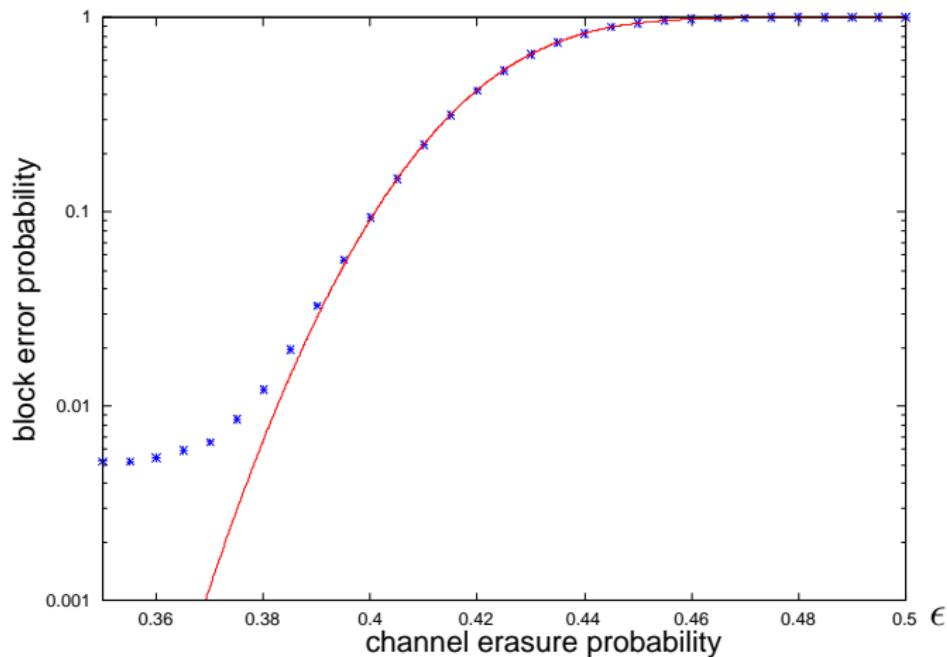
July 3th 2009

Finite-length scaling [Amraoui, et al. '03]



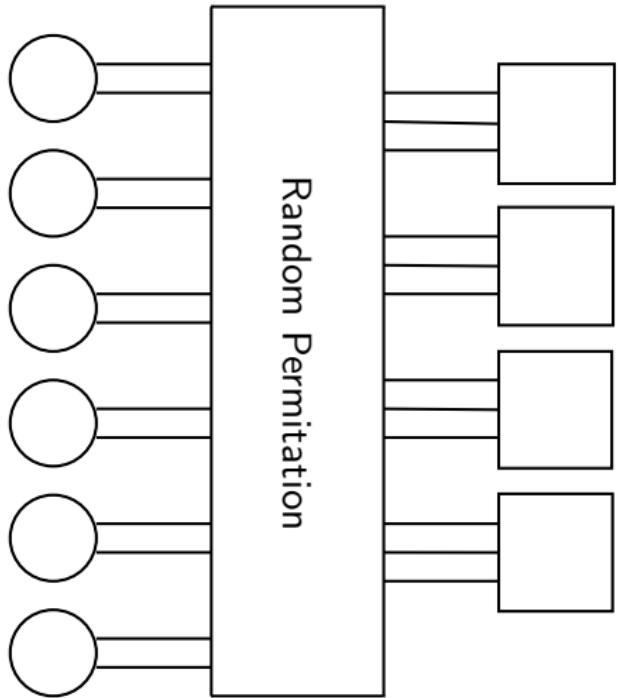
(3,6)-regular, block-length 1024

Finite-length scaling [Amraoui, et al. '03]



(3,6)-regular, block-length 1024

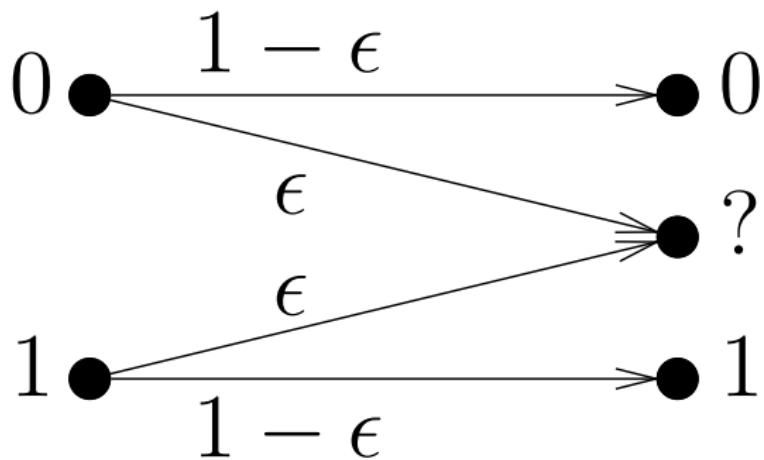
Regular LDPC code ensemble



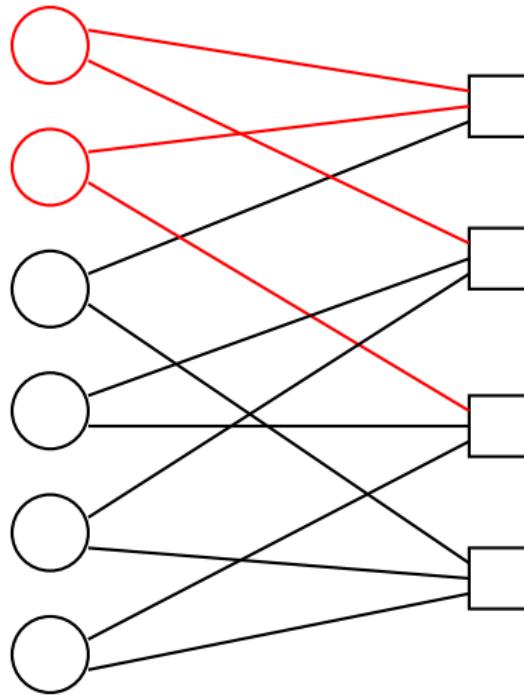
(2,3)-regular LDPC
code ensemble

○ : variable node
□ : check node

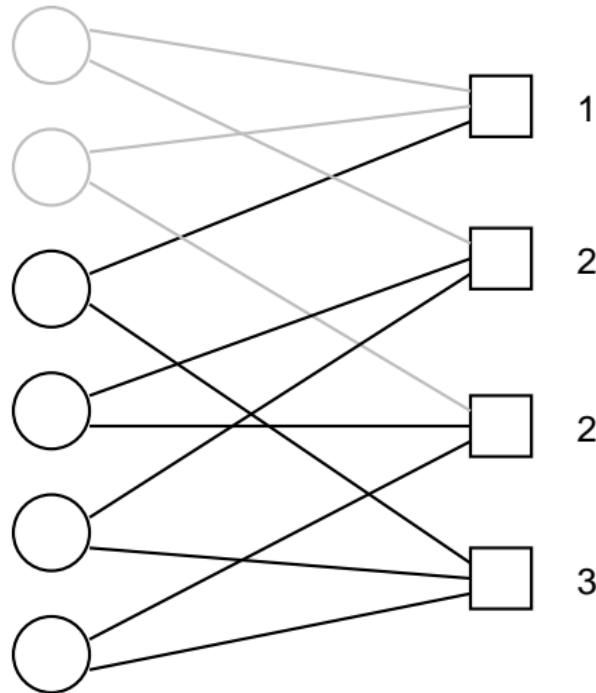
Binary Erasure Channel : BEC



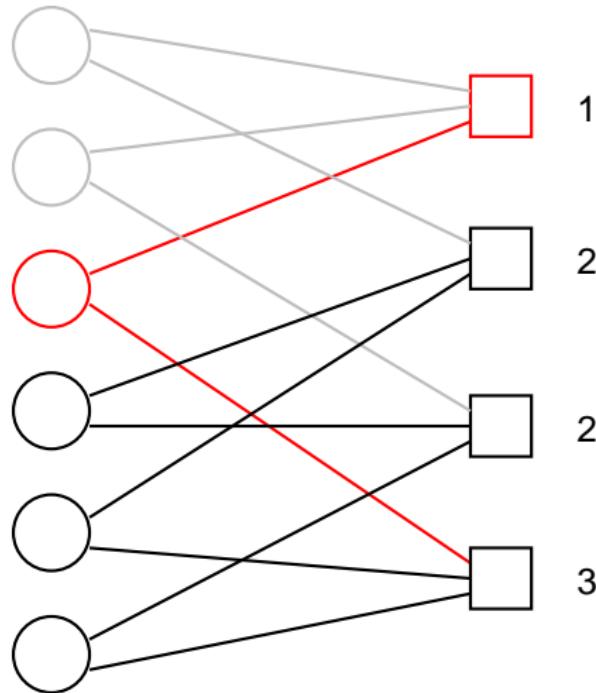
Peeling Algorithm [Luby '97]



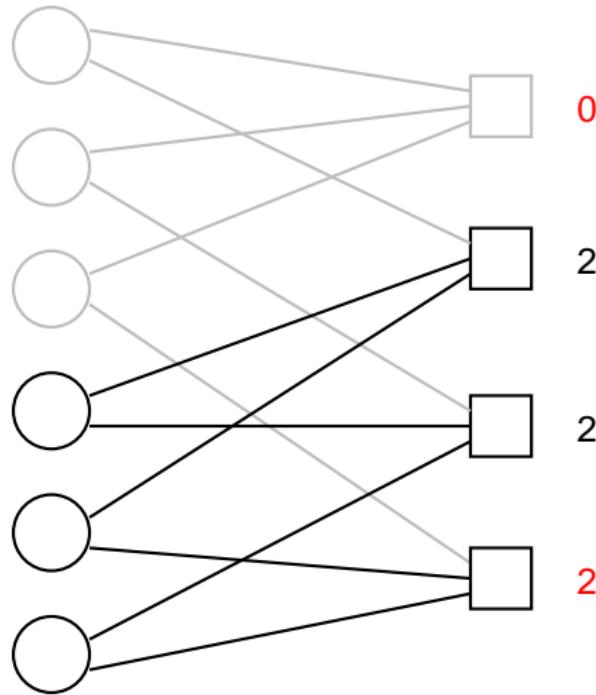
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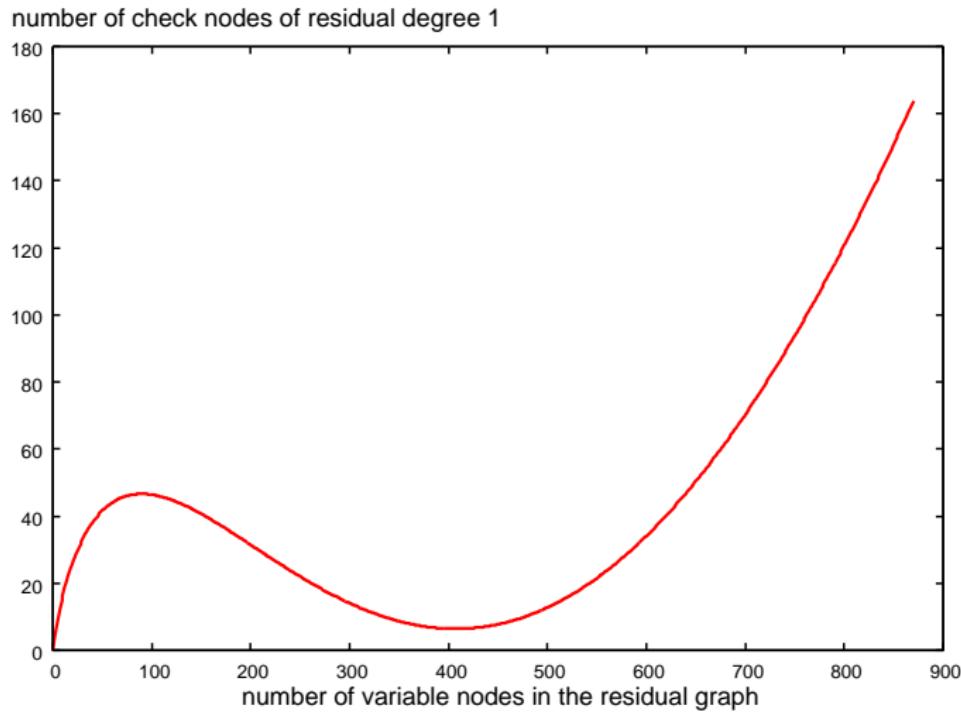
Peeling Algorithm [Luby '97]



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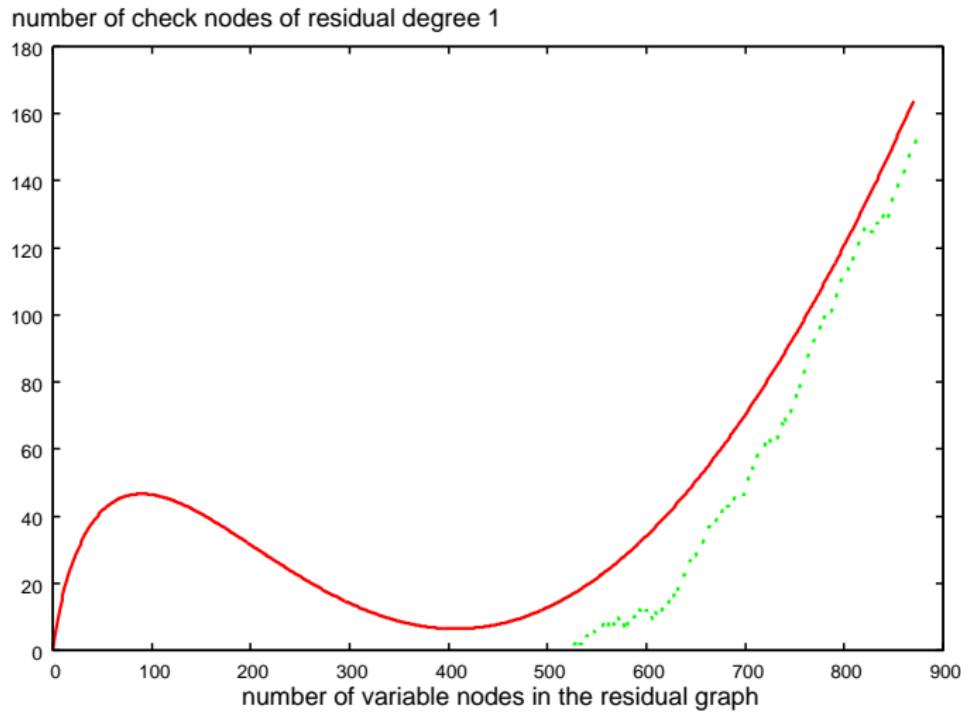


The number of check nodes of residual degree 1



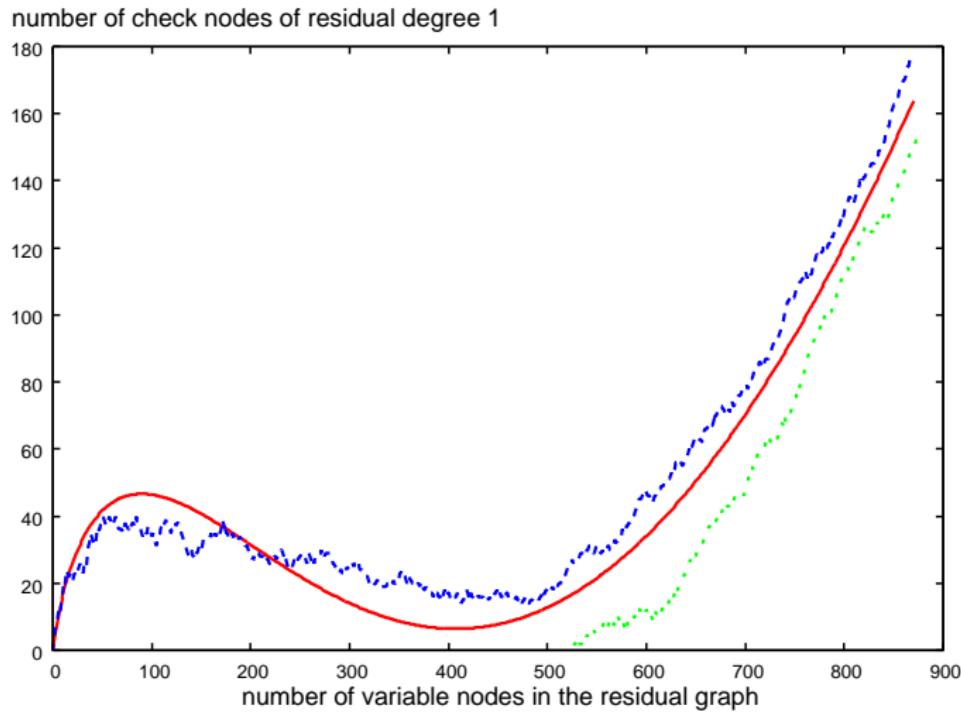
(3,6)-regular, block-length 2048, channel erasure probability 0.425

The number of check nodes of residual degree 1



(3,6)-regular, block-length 2048, channel erasure probability 0.425

The number of check nodes of residual degree 1

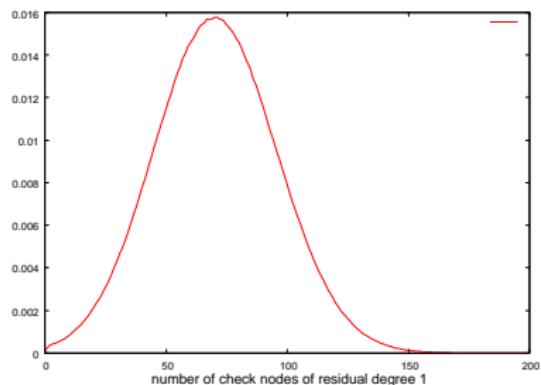
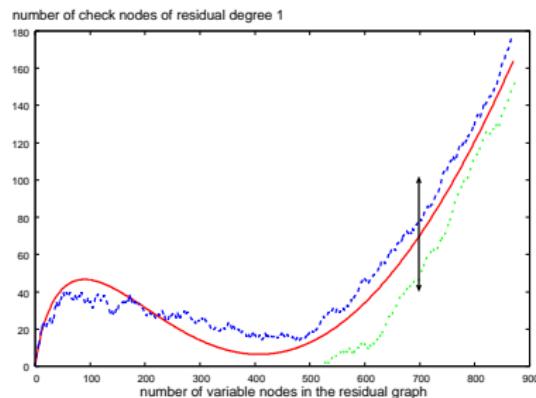


(3,6)-regular, block-length 2048, channel erasure probability 0.425

Distribution of the number of check nodes of residual degree 1 [Amraoui, et al. '03]

Amraoui, et al '03

The distribution of the number of check nodes of residual degree 1 converge weakly to normal distribution.



(3,6)-regular ensemble, block-length 2048, channel erasure probability 0.425

The variance of the number of check node of residual degree 1 [Amraoui, et al. '03]

- numerical computations for covariance evolution
- the variance of the number of erased message

Definition of the covariances

Definition of the covariance

$$\delta^{(I_b, I_b)}(y) := \frac{\text{Cov}(I_b(y), I_b(y))}{\# \text{ (edges in original graph)}}$$
$$\delta^{(I_b, r_j)}(y) := \frac{\text{Cov}(I_b(y), r_j(y))}{\# \text{ (edges in original graph)}}$$
$$\delta^{(r_j, r_k)}(y) := \frac{\text{Cov}(r_j(y), r_k(y))}{\# \text{ (edges in original graph)}}$$

$I_b(y) := \# \text{ (edges connecting to variable node of residual degree } b)$

$r_j(y) := \# \text{ (edges connecting to check node of residual degree } j)$
 $(j \in \{1, 2, \dots, d - 1\})$

$y := (\text{parameter determined from the iteration number of PA})$

Result

Theorem 1

For (b,d) -regular LDPC code ensemble,

$$\delta^{(I_b, I_b)}(y) = b\epsilon\tilde{\epsilon},$$

$$\delta^{(I_b, r_j)}(y) = -G_j\{\epsilon\tilde{\epsilon}(b-1)y^{-1} + \tilde{\epsilon}x\} + I_{\{j=1\}}b\epsilon\tilde{\epsilon},$$

$$\begin{aligned}\delta^{(r_k, r_j)}(y) &= \frac{b-1}{b}G_k G_j\{\epsilon\tilde{\epsilon}(b-1)y^{-2} - (\epsilon - \tilde{\epsilon})xy^{-1} + x^2\} \\ &\quad - d\binom{d-1}{k-1}\binom{d-1}{j-1}x^{j+k}\tilde{x}^{2d-k-j} + I_{\{k=j\}}\binom{d-1}{k-1}kx^k\tilde{x}^{d-k} \\ &\quad + I_{\{k=1, j=1\}}(b\epsilon\tilde{\epsilon} - x\tilde{x}) - (I_{\{k=1\}}G_j + I_{\{j=1\}}G_k)\{\epsilon\tilde{\epsilon}(b-1)y^{-1} - \epsilon x + x^2\}\end{aligned}$$

ϵ : channel erasure probability

$$x := \epsilon y^{b-1}, \quad \tilde{\epsilon} := 1 - \epsilon, \quad \tilde{x} := 1 - x,$$

$$G_j := \binom{d-1}{j-1}x^{j-1}\tilde{x}^{d-j-1}(dx - j) + I_{\{j=1\}}$$

Result

$$\begin{aligned}\delta^{(r_1, r_1)}(y) = & \frac{b-1}{b} G_1^2 \{ \epsilon \tilde{\epsilon} (b-1) y^{-2} - (\epsilon - \tilde{\epsilon}) x y^{-1} + x^2 \} \\ & - d x^2 \tilde{x}^{2d-2} + x \tilde{x}^{d-1} \\ & + (b \epsilon \tilde{\epsilon} - x \tilde{x}) - 2 G_1 \{ \epsilon \tilde{\epsilon} (b-1) y^{-1} - \epsilon x + x^2 \},\end{aligned}$$

where $G_1 := \tilde{x}^{d-j-1} (dx - 1) + 1$

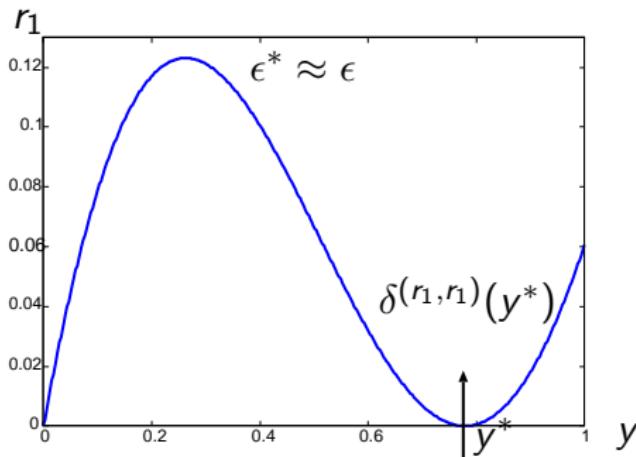
Result

corollary 1

ϵ^* : threshold of the ensemble under BP decoding
for $\epsilon = \epsilon^*$

$$\delta^{(r_1, r_1)}(y^*) = \frac{x^* y^*}{b-1} (y^* - x^*)$$

The same result as in [Amraoui '06] for regular LDPC code ensemble.



y^* : critical point,
 $x^* := \epsilon^*(y^*)^{b-1}$

Outline of proof

Solve the system of differential equation (covariance evolution) [Amraoui '06]

$$\frac{d\boldsymbol{\delta}}{dy} = F(y)\boldsymbol{\delta}(y) + \mathbf{b}(y)$$

Outline of proof

Solve the system of differential equation (covariance evolution) [Amraoui '06])

$$\frac{d\delta^{(I_b, I_b)}}{dy}(y) = 0,$$

$$\frac{d\delta^{(I_b, r_{d-1})}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{l}_b} \delta^{(I_b, I_b)} + \sum_{s=1}^{d-1} \frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{r}_s} \delta^{(I_b, r_s)} \right],$$

$$\frac{d\delta^{(I_b, r_k)}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_k)}}{\partial \bar{l}_b} \delta^{(I_b, I_b)} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_{k+1}} \delta^{(I_b, r_{k+1})} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_k} \delta^{(I_b, r_k)} \right].$$

Outline of proof

Solve the system of differential equation (covariance evolution) [Amraoui '06])

$$\delta^{(l_b, l_b)}(y) = b\epsilon\tilde{\epsilon},$$

$$\frac{d\delta^{(l_b, r_{d-1})}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{l}_b} b\epsilon\tilde{\epsilon} + \sum_{s=1}^{d-1} \frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{r}_s} \delta^{(l_b, r_s)} \right],$$

$$\frac{d\delta^{(l_b, r_k)}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_k)}}{\partial \bar{l}_b} b\epsilon\tilde{\epsilon} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_{k+1}} \delta^{(l_b, r_{k+1})} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_k} \delta^{(l_b, r_k)} \right].$$

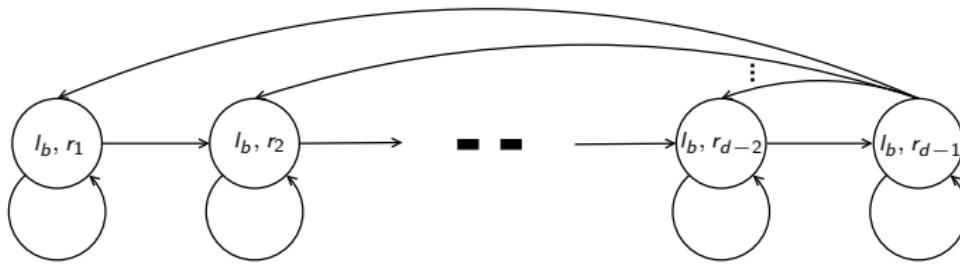
Outline of proof

Solve the system of differential equation (covariance evolution) [Amraoui '06])

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$$\frac{d\delta^{(l_b, r_k)}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_k)}}{\partial \bar{l}_b} b\epsilon\tilde{\epsilon} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_{k+1}} \delta^{(l_b, r_{k+1})} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_k} \delta^{(l_b, r_k)} \right].$$



Outline of proof

$$\textcolor{red}{A}(y) := \sum_{s=1}^{d-1} \delta^{(l_b, r_s)}$$

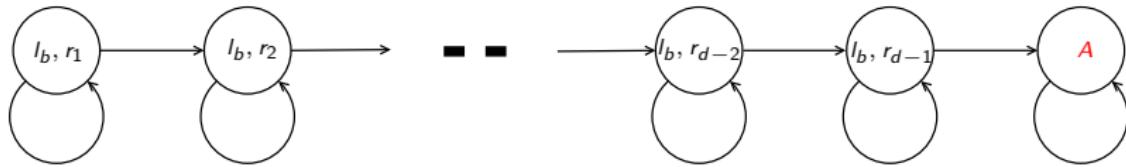
Outline of proof

$$A(y) := \sum_{s=1}^{d-1} \delta(l_b, r_s)$$

$$\frac{dA}{dy}(y) = d(b-1)y^{-1}A + d(b-1)(x^{d-1}y^{-2} - y^{-1})b\epsilon\tilde{\epsilon},$$

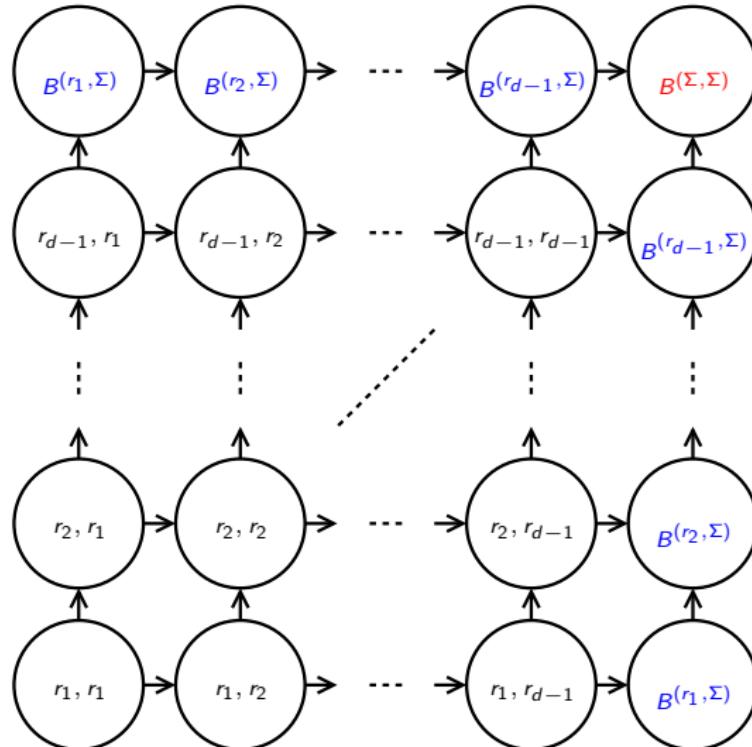
$$\frac{d\delta^{(l_b, r_{d-1})}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{l}_b} b \epsilon \tilde{\epsilon} + \frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{r}_1} A + \frac{\partial \hat{f}^{(r_{d-1})}}{\partial \bar{r}_1} \delta^{(l_b, r_{d-1})} \right],$$

$$\frac{d\delta^{(l_b, r_k)}}{dy}(y) = -x \left[\frac{\partial \hat{f}^{(r_k)}}{\partial \bar{l}_b} b \epsilon \tilde{\epsilon} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_{k+1}} \delta^{(l_b, r_{k+1})} + \frac{\partial \hat{f}^{(r_k)}}{\partial \bar{r}_k} \delta^{(l_b, r_k)} \right].$$

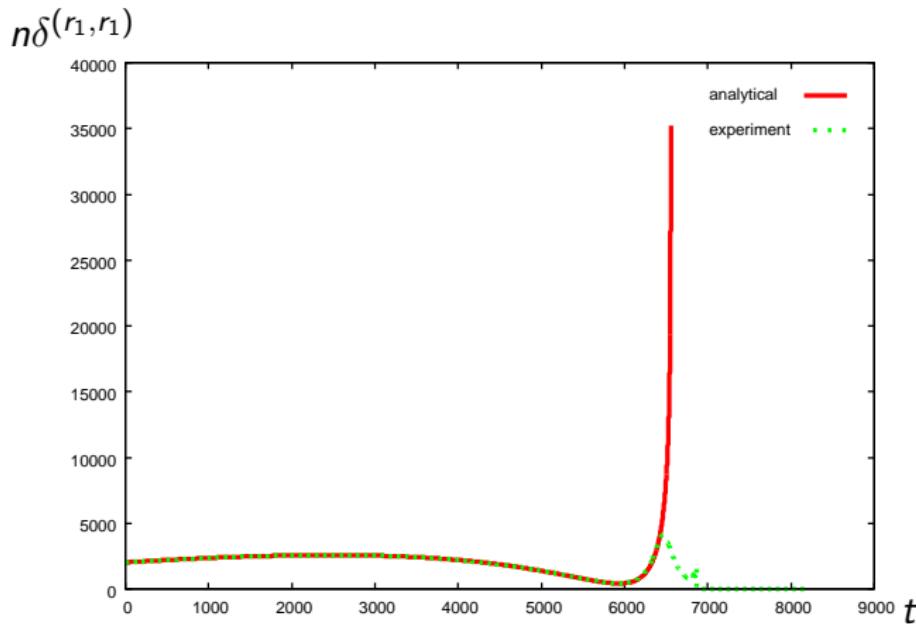


Outline of proof

$$B^{(r_j, \Sigma)} := \sum_{s=1}^{d-1} \delta(r_j, r_s), \quad B^{(\Sigma, \Sigma)} := \sum_{j=1}^{d-1} \sum_{s=1}^{d-1} \delta(r_j, r_s)$$



numerically computation



(3,6)-regular LDPC code ensemble,
block length 16384, channel erasure probability 0.400

Relationship between stability condition

corollary 2

$$\rho_{I_b, r_1}(\epsilon) = \begin{cases} 1, & \text{if } I_{\{b=2\}}(d-1)\epsilon \leq 1 \\ -1, & \text{if } I_{\{b=2\}}(d-1)\epsilon > 1. \end{cases}$$

$I_{\{b=2\}}(d-1)\epsilon < 1$: stability condition

where,

$$\rho_{I_b, r_1}(\epsilon) := \lim_{y \rightarrow 0} \frac{\delta^{(I_b, r_1)}(\epsilon, y)}{\sqrt{\delta^{(I_b, I_b)}(\epsilon, y) \delta^{(r_1, r_1)}(\epsilon, y)}},$$

Conclusion and Future Work

Conclusion

- We show the analytical solution of the covariance evolution for regular LDPC code ensembles
- We have derived the relationship between stability condition

Future Work

- Show the analytical solution of the covariance evolution for irregular LDPC code ensembles

Bibliography

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-  T. Richardson and R. Urbanke, *Modern Coding Theory*, Cambridge University Press, 2008.